## 7 TECHNICAL DETAILS OF SKETCH PLANE WIDGET

Below are helpful equations and illustrations that describe how 2D touches are mapped to 3D manipulations for translating and rotating the sketch plane widget $(\pi)$ with respect to the selected axis $\left(\pi_{\mathrm{a}}\right)$, bezel $\left(\pi_{\mathrm{b}}\right)$, or center $\left(\pi_{\mathrm{c}}\right)$ with 1 or 2 fingers.

### 7.1 Rotation About an Axis (Fig. 6b)

A sketch plane widget $\pi$ is defined in terms of a position $\mathbf{X}$, normal $\mathbf{n}$, and two axial directions $\mathbf{a}_{1}$ and $\mathbf{a}_{2}$. Its movement can be expressed as:

$$
\pi:\left\{\mathbf{X}, \mathbf{n}, \mathbf{a}_{1}, \mathbf{a}_{2}\right\} \rightarrow \pi^{\prime}:\left\{\mathbf{X}^{\prime}, \mathbf{n}^{\prime}, \mathbf{a}_{1}^{\prime}, \mathbf{a}_{2}^{\prime}\right\}
$$

When an axis $\pi_{\mathrm{a}}$ with the direction $\mathbf{a}_{1}$ is selected and a touch is made at $\mathbf{T}_{1}$, the touch point is projected as $\mathbf{P}_{1}$ by the intersection of a line $l\left(\mathbf{E}, \mathbf{T}_{1}\right)$ that connects the eye $\mathbf{E}$ to $\mathbf{T}_{1}$ with a plane $\mathrm{p}(\mathbf{X}, \mathbf{n})$ that contains $\mathbf{X}$ and has the normal $\mathbf{n}$ :

$$
\mathbf{P}_{1}=l\left(\mathbf{E}, \mathbf{T}_{1}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n})
$$

Then, a second plane $\mathrm{p}\left(\mathbf{C}, \mathbf{a}_{1}\right)$ is defined, where the position $\mathbf{C}$ it contains is calculated as:

$$
\mathbf{C}=\mathbf{X}+\left(\left(\mathbf{P}_{1}-\mathbf{X}\right) \cdot \mathbf{a}_{1}\right) \mathbf{a}_{1}
$$

When the touch is dragged to $\mathbf{T}_{1}^{\prime}$, it is projected onto the second plane $\mathrm{p}\left(\mathbf{C}, \mathbf{a}_{1}\right)$ as $\mathbf{P}_{1}^{\prime}$ :

$$
\mathbf{P}_{1}^{\prime}=l\left(\mathbf{E}, \mathbf{T}_{1}^{\prime}\right) \cap \mathrm{p}\left(\mathbf{C}, \mathbf{a}_{1}\right)
$$

Finally, the sketch plane widget $\pi$ is moved to $\pi^{\prime}$ so that:

$$
\begin{gathered}
\mathbf{X}^{\prime}=\mathbf{X} \\
\mathbf{a}_{1}^{\prime}=\mathbf{a}_{1} \\
\mathbf{a}_{2}^{\prime}=\frac{\mathbf{P}_{1}^{\prime}-\mathbf{C}}{\left\|\mathbf{P}_{1}^{\prime}-\mathbf{C}\right\|} \\
\mathbf{n}^{\prime}=\mathbf{a}_{1}^{\prime} \times \mathbf{a}_{2}^{\prime}
\end{gathered}
$$



### 7.2 Translation Along an Axis (Fig. 6c)

A sketch plane widget $\pi$ is defined in terms of a position $\mathbf{X}$, normal $\mathbf{n}$, and two axial directions $\mathbf{a}_{1}$ and $\mathbf{a}_{2}$. Its movement can be expressed as:

$$
\pi:\left\{\mathbf{X}, \mathbf{n}, \mathbf{a}_{1}, \mathbf{a}_{2}\right\} \rightarrow \pi^{\prime}:\left\{\mathbf{X}^{\prime}, \mathbf{n}^{\prime}, \mathbf{a}_{1}^{\prime}, \mathbf{a}_{2}^{\prime}\right\}
$$

When an axis $\pi_{a}$ with the direction $\mathbf{a}_{1}$ is selected and two touches are made at $\mathbf{T}_{1}$ and $\mathbf{T}_{2}$, the touch points are projected as $\mathbf{P}_{1}$ and $\mathbf{P}_{2}$ by the intersections of lines $l\left(\mathbf{E}, \mathbf{T}_{1}\right)$ and $l\left(\mathbf{E}, \mathbf{T}_{2}\right)$ that connect the eye $\mathbf{E}$ to $\mathbf{T}_{1}$ and $\mathbf{T}_{2}$ with a plane $p(\mathbf{X}, \mathbf{n})$ that contains $\mathbf{X}$ and has the normal $\mathbf{n}$ :

$$
\begin{aligned}
& \mathbf{P}_{1}=\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{1}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n}) \\
& \mathbf{P}_{2}=\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{2}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n})
\end{aligned}
$$

The midpoint between the two points $\mathbf{P}_{1}$ and $\mathbf{P}_{2}$ is calculated as $\mathbf{P}_{\mathrm{m}}$ :

$$
\mathbf{P}_{\mathrm{m}}=\frac{\mathbf{P}_{1}+\mathbf{P}_{2}}{2}
$$

When the touches are dragged to $\mathbf{T}_{1}^{\prime}$ and $\mathbf{T}_{2}^{\prime}$, their projections on the same plane $\mathrm{p}(\mathbf{X}, \mathbf{n})$ and the midpoint between those projections are calculated as $\mathbf{P}_{1}^{\prime}, \mathbf{P}_{1}^{\prime}$, and $\mathbf{P}_{\mathrm{m}}^{\prime}$ :

$$
\begin{gathered}
\mathbf{P}_{1}^{\prime}=\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{1}^{\prime}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n}) \\
\mathbf{P}_{2}^{\prime}=\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{2}^{\prime}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n}) \\
\mathbf{P}_{\mathrm{m}}^{\prime}=\frac{\mathbf{P}_{1}^{\prime}+\mathbf{P}_{2}^{\prime}}{2}
\end{gathered}
$$

Finally, the sketch plane widget $\pi$ is moved to $\pi^{\prime}$ so that:

$$
\begin{gathered}
\mathbf{X}^{\prime}=\mathbf{X}+\left(\left(\mathbf{P}_{\mathrm{m}}^{\prime}-\mathbf{P}_{\mathrm{m}}\right) \cdot \mathbf{a}_{1}\right) \mathbf{a}_{1} \\
\mathbf{a}_{1}^{\prime}=\mathbf{a}_{1} \\
\mathbf{a}_{2}^{\prime}=\mathbf{a}_{2} \\
\mathbf{n}^{\prime}=\mathbf{n}
\end{gathered}
$$



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### 7.3 Translation on the Plane (Fig. 6e)

A sketch plane widget $\pi$ is defined in terms of a position $\mathbf{X}$, normal $\mathbf{n}$, and two axial directions $\mathbf{a}_{1}$ and $\mathbf{a}_{2}$. Its movement can be expressed as:

$$
\pi:\left\{\mathbf{X}, \mathbf{n}, \mathbf{a}_{1}, \mathbf{a}_{2}\right\} \rightarrow \pi^{\prime}:\left\{\mathbf{X}^{\prime}, \mathbf{n}^{\prime}, \mathbf{a}_{1}^{\prime}, \mathbf{a}_{2}^{\prime}\right\}
$$

When the bezel $\pi_{\mathrm{b}}$ is selected and a touch is made at $\mathbf{T}_{1}$, the touch point is projected as $\mathbf{P}_{1}$ by the intersection of a line $l\left(\mathbf{E}, \mathbf{T}_{1}\right)$ that connects the eye $\mathbf{E}$ to $\mathbf{T}_{1}$ with a plane $\mathrm{p}(\mathbf{X}, \mathbf{n})$ that contains $\mathbf{X}$ and has the normal $\mathbf{n}$ :

$$
\mathbf{P}_{1}=l\left(\mathbf{E}, \mathbf{T}_{1}\right) \cap p(\mathbf{X}, \mathbf{n})
$$

When the touch is dragged to $\mathbf{T}_{1}^{\prime}$, it is projected on the same plane $\mathrm{p}(\mathbf{X}, \mathbf{n})$ as $\mathbf{P}_{1}^{\prime}$ :

$$
\mathbf{P}_{1}^{\prime}=l\left(\mathbf{E}, \mathbf{T}_{1}^{\prime}\right) \cap p(\mathbf{X}, \mathbf{n})
$$

Finally, the sketch plane widget $\pi$ is moved to $\pi^{\prime}$ so that:

$$
\begin{gathered}
\mathbf{X}^{\prime}=\mathbf{X}+\left(\mathbf{P}_{1}^{\prime}-\mathbf{P}_{1}\right) \\
\mathbf{a}_{1}^{\prime}=\mathbf{a}_{1} \\
\mathbf{a}_{2}^{\prime}=\mathbf{a}_{2} \\
\mathbf{n}^{\prime}=\mathbf{n}
\end{gathered}
$$

### 7.4 Translation and Rotation on the Plane (Fig. 6f)

A sketch plane widget $\pi$ is defined in terms of a position $\mathbf{X}$, normal $\mathbf{n}$, and two axial directions $\mathbf{a}_{1}$ and $\mathbf{a}_{2}$. Its movement can be expressed as:

$$
\pi:\left\{\mathbf{X}, \mathbf{n}, \mathbf{a}_{1}, \mathbf{a}_{2}\right\} \rightarrow \pi^{\prime}:\left\{\mathbf{X}^{\prime}, \mathbf{n}^{\prime}, \mathbf{a}_{1}^{\prime}, \mathbf{a}_{2}^{\prime}\right\}
$$

When the bezel $\pi_{\mathrm{b}}$ is selected and two touches are made at $\mathbf{T}_{1}$ and $\mathbf{T}_{2}$, the touch points are projected as $\mathbf{P}_{1}$ and $\mathbf{P}_{2}$ by the intersections of lines $\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{1}\right)$ and $\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{2}\right)$ that connect the eye $\mathbf{E}$ to $\mathbf{T}_{1}$ and $\mathbf{T}_{2}$ with a plane $p(\mathbf{X}, \mathbf{n})$ that contains $\mathbf{X}$ and has the normal $\mathbf{n}$ :

$$
\begin{aligned}
& \mathbf{P}_{1}=\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{1}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n}) \\
& \mathbf{P}_{2}=\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{2}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n})
\end{aligned}
$$

The midpoint between the two points $\mathbf{P}_{1}$ and $\mathbf{P}_{2}$ is calculated as $\mathbf{P}_{\mathrm{m}}$ :

$$
\mathbf{P}_{\mathrm{m}}=\frac{\mathbf{P}_{1}+\mathbf{P}_{2}}{2}
$$

When the touches are dragged to $\mathbf{T}_{1}^{\prime}$ and $\mathbf{T}_{2}^{\prime}$, their projections on the same plane $\mathrm{p}(\mathbf{X}, \mathbf{n})$ and the midpoint between those projections are calculated as $\mathbf{P}_{1}^{\prime}, \mathbf{P}_{2}^{\prime}$, and $\mathbf{P}_{\mathrm{m}}^{\prime}$ :

$$
\begin{gathered}
\mathbf{P}_{1}^{\prime}=\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{1}^{\prime}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n}) \\
\mathbf{P}_{2}^{\prime}=\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{2}^{\prime}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n}) \\
\mathbf{P}_{\mathrm{m}}^{\prime}=\frac{\mathbf{P}_{1}^{\prime}+\mathbf{P}_{2}^{\prime}}{2}
\end{gathered}
$$

Then, a quaternion $\mathbf{q}$ that expresses the rotation of unit vectors from $\frac{\mathbf{P}_{2}-\mathbf{P}_{1}}{\left\|\mathbf{P}_{2}-\mathbf{P}_{1}\right\|}$ to $\frac{\mathbf{P}_{2}^{\prime}-\mathbf{P}_{1}^{\prime}}{\left\|\mathbf{P}_{2}^{\prime}-\mathbf{P}_{1}^{\prime}\right\|}$ is calculated.

Finally, the sketch plane widget $\pi$ is moved to $\pi^{\prime}$ so that:

$$
\begin{gathered}
\mathbf{X}^{\prime}=\mathbf{X}+\left(\mathbf{P}_{\mathrm{m}}^{\prime}-\mathbf{P}_{\mathrm{m}}\right) \\
\mathbf{a}_{1}^{\prime}=\mathbf{q} \mathbf{a}_{1} \mathbf{q}^{-1} \\
\mathbf{a}_{2}^{\prime}=\mathbf{q} \mathbf{a}_{2} \mathbf{q}^{-1} \\
\mathbf{n}^{\prime}=\mathbf{n}
\end{gathered}
$$



### 7.5 Orbit About the Center (Fig. 6h)

A sketch plane widget $\pi$ is defined in terms of a position $\mathbf{X}$, normal $\mathbf{n}$, and two axial directions $\mathbf{a}_{1}$ and $\mathbf{a}_{2}$. Its movement can be expressed as:

$$
\pi:\left\{\mathbf{X}, \mathbf{n}, \mathbf{a}_{1}, \mathbf{a}_{2}\right\} \rightarrow \pi^{\prime}:\left\{\mathbf{X}^{\prime}, \mathbf{n}^{\prime}, \mathbf{a}_{1}^{\prime}, \mathbf{a}_{2}^{\prime}\right\}
$$

When the center $\pi_{\mathrm{c}}$ is selected and a touch is made at $\mathbf{T}_{1}$, the touch point is projected as $\mathbf{P}_{1}$ by the intersection of a line $\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{1}\right)$ that connects the eye $\mathbf{E}$ to $\mathbf{T}_{1}$ with a plane $p(\mathbf{X}, \mathbf{n})$ that contains $\mathbf{X}$ and has the normal $\mathbf{n}$ :

$$
\mathbf{P}_{1}=l\left(\mathbf{E}, \mathbf{T}_{1}\right) \cap \mathrm{p}(\mathbf{X}, \mathbf{n})
$$

Then, a sphere $s(\mathbf{X}, r)$ that is located at $\mathbf{X}$ and has a radius of r is defined, where:

$$
\mathrm{r}=\left\|\mathbf{P}_{1}-\mathbf{X}\right\|
$$

When the touch is dragged to $\mathbf{T}_{1}^{\prime}$, it is projected onto the sphere $\mathrm{s}(\mathbf{X}, \mathrm{r})$ as $\mathbf{P}_{1}^{\prime}$ :

$$
\mathbf{P}_{1}^{\prime}=l\left(\mathbf{E}, \mathbf{T}_{1}^{\prime}\right) \cap s(\mathbf{X}, \mathrm{r})
$$

Then, for the case in which the line $l\left(\mathbf{E}, \mathbf{T}_{1}^{\prime}\right)$ and sphere $s(\mathbf{X}, r)$ intersect, a quaternion $\mathbf{q}_{0}$ that expresses the rotation of unit vectors from $\frac{\mathbf{P}_{1}-\mathbf{X}}{\left\|\mathbf{P}_{1}-\mathbf{X}\right\|}$ to $\frac{\mathbf{P}_{1}^{\prime}-\mathbf{X}}{\left\|\mathbf{P}_{1}^{\prime}-\mathbf{X}\right\|}$ is calculated.

Finally, the sketch plane widget $\pi$ is moved to $\pi^{\prime}$ so that:

$$
\begin{gathered}
\mathbf{X}^{\prime}=\mathbf{X} \\
\mathbf{a}_{1}^{\prime}=\mathbf{q}_{\mathbf{o}} \mathbf{a}_{1} \mathbf{q}_{0}^{-1} \\
\mathbf{a}_{2}^{\prime}=\mathbf{q}_{\mathbf{o}} \mathbf{a}_{2} \mathbf{q}_{0}^{-1} \\
\mathbf{n}^{\prime}=\mathbf{a}_{1}^{\prime} \times \mathbf{a}_{2}^{\prime}
\end{gathered}
$$



### 7.6 Orbit and Spin About the Center (Fig. 6i)

Continuing from the sketch plane widget $\pi^{\prime}$ that orbited about the center $\pi_{\mathrm{c}}$, additional movement from spinning can be expressed as:

$$
\pi^{\prime}:\left\{\mathbf{X}^{\prime}, \mathbf{n}^{\prime}, \mathbf{a}_{1}^{\prime}, \mathbf{a}_{2}^{\prime}\right\} \rightarrow \pi^{\prime \prime}:\left\{\mathbf{X}^{\prime \prime}, \mathbf{n}^{\prime \prime}, \mathbf{a}_{1}^{\prime \prime}, \mathbf{a}_{2}^{\prime \prime}\right\}
$$

When a second touch is made at $\mathbf{T}_{2}$, it is projected onto the sphere $\mathrm{s}(\mathbf{X}, \mathrm{r})$ as $\mathbf{P}_{2}$ :

$$
\mathbf{P}_{2}=1\left(\mathbf{E}, \mathbf{T}_{2}\right) \cap \mathrm{s}(\mathbf{X}, \mathrm{r})
$$

Then, for the case in which the line $\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{2}\right)$ and sphere $\mathrm{s}(\mathbf{X}, r)$ intersect, a second plane $\mathrm{p}\left(\mathbf{C}, \mathbf{n}_{\mathrm{c}}\right)$ is defined, where the position $\mathbf{C}$ it contains and its normal $\mathbf{n}_{\mathrm{c}}$ are calculated:

$$
\begin{gathered}
\mathbf{n}_{\mathrm{c}}=\frac{\mathbf{P}_{1}^{\prime}-\mathbf{X}}{\left\|\mathbf{P}_{1}^{\prime}-\mathbf{X}\right\|} \\
\mathbf{C}=\mathbf{X}+\left(\left(\mathbf{P}_{2}-\mathbf{X}\right) \cdot \mathbf{n}_{\mathrm{c}}\right) \mathbf{n}_{\mathrm{c}}
\end{gathered}
$$

When the second touch is dragged to $\mathbf{T}_{2}^{\prime}$, it is projected onto the second plane $\mathrm{p}\left(\mathbf{C}, \mathbf{n}_{\mathrm{c}}\right)$ as $\mathbf{P}_{2}^{\prime}$ :

$$
\mathbf{P}_{2}^{\prime}=\mathrm{l}\left(\mathbf{E}, \mathbf{T}_{2}^{\prime}\right) \cap \mathrm{p}\left(\mathbf{C}, \mathbf{n}_{\mathrm{c}}\right)
$$

Then, a quaternion $\mathbf{q}_{\mathrm{s}}$ that expresses the rotation of unit vectors from $\frac{\mathbf{P}_{2}-\mathbf{C}}{\left\|\mathbf{P}_{2}-\mathbf{C}\right\|}$ to $\frac{\mathbf{P}_{2}^{\prime}-\mathbf{C}}{\left\|\mathbf{P}_{2}^{\prime}-\mathbf{C}\right\|}$ is calculated.

Finally, the sketch plane widget $\pi^{\prime}$ is moved to $\pi^{\prime \prime}$ so that:

$$
\begin{gathered}
\mathbf{X}^{\prime \prime}=\mathbf{X}^{\prime} \\
\mathbf{a}_{1}^{\prime \prime}=\mathbf{q}_{\mathbf{s}} \mathbf{a}_{1}^{\prime} \mathbf{q}_{\mathbf{s}}^{-1} \\
\mathbf{a}_{2}^{\prime \prime}=\mathbf{q}_{\mathbf{s}} \mathbf{a}_{2}^{\prime} \mathbf{q}_{\mathrm{s}}^{-1} \\
\mathbf{n}^{\prime \prime}=\mathbf{a}_{1}^{\prime \prime} \times \mathbf{a}_{2}^{\prime \prime}
\end{gathered}
$$



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